Pseudospectral Methods and Instability in Rotating Shallow Water Boeing, February 2020

W.R. Casper

Department of Mathematics Louisiana State University

February 12, 2020

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Outline

Rotating Shallow Water

- Shallow Water Equations
- Quasi-geostrophic model
- Pseudospectral Techniques

Instability Analysis

- Rayleigh's Equation
- Sine Profile Instability
- Comparison with Shallow Water

3 Analytic Methods for the Cosine Profile

- Orthogonal Polynomials
- Relation to Instability
- Calculating Instability

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Shallow Water Equations Quasi-geostrophic model Pseudospectral Techniques

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Geophysical Length Scales

- typical length scale of flow in the ocean: 15,000 km
- typical ocean depth: 3 km
- typical thickness of a sheet of paper: 0.0039 in

On a global scale the ocean is a paper-thin sheet on the surface of a basketball.

we can model a patch of ocean as a shallow water

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The Shallow Water Equations

Shallow Water Equations

$$ec{u}_t + ec{u} \cdot
abla ec{u} = ec{u} imes f \hat{z} - g
abla \eta$$

 $\eta_t + (H + \eta)
abla \cdot ec{u} + ec{u} \cdot (
abla \eta) = 0$

- η free surface height
- H mean depth
- \vec{u} the (horizontal) fluid velocity

(!!) Assumes $H/L \ll 1$ where L is length scale of interest

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Non-dimensional Form

Non-dimensional Shallow Water Equations

$$\vec{u}_t + \vec{u} \cdot \nabla \vec{u} = \frac{1}{\text{Ro}} \vec{u} \times \hat{z} - \frac{1}{\text{Ro}} \nabla \eta$$
$$\eta_t + \left(\frac{\text{Bu}}{\text{Ro}} + \eta\right) \nabla \cdot \vec{u} + \vec{u} \cdot (\nabla \eta) = 0$$

• Ro =
$$U/(fL)$$

• Fr = U/\sqrt{gH}
• Bu = $(\text{Ro}/\text{Fr})^2 = (L_d/L)^2$ for L_d Rossby deformation radius

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Linearized Shallow Water

Linearizing around $\eta = 0$ and $\vec{u} = 0$:

$$u = \widetilde{u}(t)e^{ik_x x + ik_y y}, \quad v = \widetilde{v}(t)e^{ik_x x + ik_y y}, \quad \eta = \widetilde{\eta}(t)e^{ik_x x + ik_y y},$$

under which the linearized shallow water equations become

$$\begin{bmatrix} \widetilde{u} \\ \widetilde{v} \\ \widetilde{\eta}/\sqrt{\mathsf{Bu}} \end{bmatrix}' = \frac{1}{\mathsf{Ro}} \begin{bmatrix} 0 & 1 & -\sqrt{\mathsf{Bu}}ik_x \\ -1 & 0 & -\sqrt{\mathsf{Bu}}ik_y \\ -\sqrt{\mathsf{Bu}}ik_x & -\sqrt{\mathsf{Bu}}ik_y & 0 \end{bmatrix} \begin{bmatrix} \widetilde{u} \\ \widetilde{v} \\ \widetilde{\eta}/\sqrt{\mathsf{Bu}} \end{bmatrix}$$

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Slow Modes

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Slow mode:

$$\begin{bmatrix} \widetilde{u} \\ \widetilde{v} \\ \widetilde{\eta} \end{bmatrix} \propto \begin{bmatrix} -ik_y \\ ik_x \\ 1 \end{bmatrix}$$

- note that $u = -\eta_y$ and $v = \eta_x$
- we will call this geostrophic balance

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Fast Modes

Fast mode:

$$\begin{bmatrix} \widetilde{u} \\ \widetilde{v} \\ \widetilde{\eta} \end{bmatrix} \propto \begin{bmatrix} -ik_y - \lambda \operatorname{Ro} ik_x \\ ik_x - \lambda \operatorname{Ro} ik_y \\ -k^2 \operatorname{Bu} \end{bmatrix} e^{i\lambda t}$$

where here

$$\lambda = \pm \frac{1}{\text{Ro}} \sqrt{\text{Bu}(k_x^2 + k_y^2) + 1}.$$

- divergent phenomena: sound waves
- for $Ro \ll 1$, this limits simulation timesteps...

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Geostrophic Balance

- Away from the Equator: $Ro \ll 1$
- To leading order we have geostrophic balance

$$v = \eta_x$$
 and $u = -\eta_y$.

- Flow is perpendicular to the pressure gradient!
- Flow is divergence-free so no sound waves
- In dimensional coordinates

$$v = rac{g}{f}\eta_x$$
 and $u = -rac{g}{f}\eta_y$.

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Shallow Water for $Ro \ll 1$

Rossby number expansion:

$$\vec{u} = \vec{u}_0 + \vec{u}_1 \operatorname{Ro} + \mathcal{O}(\operatorname{Ro}^2)$$

 $\eta = \eta_0 + \eta_1 \operatorname{Ro} + \mathcal{O}(\operatorname{Ro}^2)$

Geostrophic decomposition:

$$ec{u}_i = ec{u}_{i,g} + ec{u}_{i,ag}, ext{ where } ec{u}_{i,g} imes ec{z} =
abla \eta_i$$

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The Quasi-geostrophic Model

Then to order 0 in Ro: $\vec{u}_{0,ag} = \vec{0}$ and

$$(\vec{u}_{0,g})_t + \vec{u}_{0,g} \cdot \nabla \vec{u}_{0,g} = \vec{u}_1 \times \hat{z} - \nabla \eta_1.$$

$$(\eta_{0,g})_t + \mathsf{Bu} \nabla \cdot \vec{u}_1 = 0.$$

This simplifies to a closed equation

$$\left(1-\frac{\Delta^{-1}}{\mathsf{Bu}}\right)(\vec{u}_{0,g})_t+\vec{u}_{0,g}\cdot\nabla\vec{u}_{0,g}=-\nabla p_{0,g},$$

where $p_{0,g}$ is the **geostrophic pressure**

$$-\Delta p_{0,g} =
abla \cdot (\vec{u}_{0,g} \cdot
abla \vec{u}_{0,g}).$$

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Stream Function Formulation

The stream function ψ satisfies

$$\vec{u}_{0,g} = \hat{z} \times \nabla \psi$$
, and $\nabla \times \vec{u}_{0,g} = -\Delta \psi$.

Taking the curl of the QG-model and simplifying:

$$oldsymbol{q}_t + oldsymbol{J}(\psi,oldsymbol{q}) = oldsymbol{0}, ext{ where } oldsymbol{J}(\psi,oldsymbol{q}) = \psi_{oldsymbol{x}}oldsymbol{q}_{oldsymbol{y}} - \psi_{oldsymbol{y}}oldsymbol{q}_{oldsymbol{x}},$$

$$q = \Delta \psi - rac{1}{\mathsf{Bu}} \psi$$
 potential vorticity

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A Simple Example

Consider the KdV equation:

$$u_t + u_{xxx} = 6uu_x.$$

Pseudo-spectral technique:

- do all products in physical space
- do all spatial derivatives in spectral space $\pi^{-1}(13\pi(x)) = 0$

$$u_t = \mathcal{F}^{-1}(ik^3\mathcal{F}(u)) + 6u\mathcal{F}^{-1}(ik\mathcal{F}(u)).$$

Important: aliasing errors

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The Code

- source code written in C
- capable of solving multiple models
 - 2 and 3-dim DNS
 - Boussinesq
 - shallow water and qg shallow water
- capable of periodic and rigid lid boundary
- uses P3DFFT for 2 or 3-dim fast Fourier transforms
 - allows pencil domain decomposition
 - scales well with thousands of processors
- diagnostic calculation, file I/O, parallelization with OpenMPI

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Initial PV



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PV at *t* = 50



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PV at *t* = 100



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PV at *t* = 150



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PV at *t* = 200



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The Evolutionary Picture

- Presence of linear instabilities causes growth of certain wave modes
- In above, instabilities caused by interactions between interfacial waves
- The fastest growing mode will be dominant
- Nonlinear advection term causes these to rotate/interact
- Eventually transitions to turbulent regime (dipole pv)

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Questions

- Energy flows from small scales to large scales (inverse scattering)
- Can we predict the number of vortices?
- How does the number of vortices vary with Ro, Fr, Bu?
- How does the picture change in the full shallow water equations?

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

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Linearized QG

Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Consider a perturbation ψ^{ρ} from a background profile ψ^{b} :

$$q_t^b+q_t^p+J(\psi^b,q^b)+J(\psi^b,q^p)+J(\psi^p,q^b)+J(\psi^p,q^p)=0,$$

Dropping nonlinear perturbation terms:

Linearized QG PV Equation

$$q^{p}_t+J(\psi^{b},q^{p})+J(\psi^{p},q^{b})=0$$

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Rayleigh Equation

Base state:

$$\psi^b = -\int u^b(y)dy$$

Linearized QG PV:

$$q_t^p + (q^b)'\psi_x^p - (\psi^b)'q_x^p = 0.$$

Substitute perturbed solution:

$$\psi^{p}(x, y, t) = e^{ik(x-ct)}f(y)$$

Rayleigh Equation:

$$f''(y) - \left(k^2 + \frac{u^b(y)'' - c/Bu}{u^b(y) - c}\right)f(y) = 0.$$

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Background Profile



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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Background Profile

$$\begin{split} u^{b}(y) &= -b\cosh(y/\sqrt{\mathsf{Bu}}), & 0 \leq y < L_{1} \\ u^{b}(y) &= m\sinh\left(\frac{y-L_{y}/4}{\sqrt{\mathsf{Bu}}}\right), & L_{1} \leq y < L_{2} \\ u^{b}(y) &= b\cosh\left(\frac{y-L_{y}/2}{\sqrt{\mathsf{Bu}}}\right)), & L_{2} \leq y < L_{3} \\ u^{b}(y) &= -m\sinh\left(\frac{y-3L_{y}/4}{\sqrt{\mathsf{Bu}}}\right), & L_{3} \leq y < L_{4} \\ u^{b}(y) &= -b\cosh\left(\frac{y-L_{y}}{\sqrt{\mathsf{Bu}}}\right), & L_{4} \leq y < L_{y} \\ m &= \frac{u}{\sinh(d/2\sqrt{\mathsf{Bu}})} \\ b &= \frac{u}{\cosh(L_{1}/\sqrt{\mathsf{Bu}})} \end{split}$$

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Analytic solution with Rayleigh

$$f_i(\mathbf{y}) = \mathbf{A}_i \mathbf{e}^{\widetilde{k}\mathbf{y}} + \mathbf{B}_i \mathbf{e}^{-\widetilde{k}\mathbf{y}}, \ i = 1, \dots, 5.$$

for $\widetilde{k} = \sqrt{k^2 + \frac{1}{Bu}}$. Jump conditions:

$$W(f(y), u^{b}(y)-c)$$
, and $\frac{f(y)}{u^{b}(y)-c}$ are continuous at interfaces.

Result in a system of linear equations for A_i, B_i . Approx. Scattering Relation:

$$\frac{c^2k^2d^2}{u^2} = \left[kd - z\frac{kd}{\sqrt{(kd)^2 + d^2/Bu}}\right]^2 - e^{-2\widetilde{k}d}\frac{(kd)^2}{(kd)^2 + d^2/Bu}z^2$$

for $z = (d/\sqrt{\mathrm{Bu}})(1 + \coth(d/2\sqrt{\mathrm{Bu}}))/2$.

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Instability Growth Rate



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Most Unstable Wave Number



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Modes are eventually stable

Theorem (Casper)

Let y_i be an inflection point of $u^b(y)$ and set $u_s = u^b(y_i)$. Let k_s^2 be the maximum eigenvalue of the discrete spectrum of

$$D(y, \partial_y) = \partial_y^2 - \frac{1}{Bu} + K(y), \ K(y) = -\frac{(u^b)''(y) - u^b(y)/Bu}{u^b(y) - u_s}.$$

with $K(y) \ge 0$ throughout the field. Then k is stable for $k \ge k_s$.

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Growth Rates



Figure: Growth rate vs. wave number for $u^{b}(y) = \sin(40y)$

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Growth Rates



Figure: Must be stable for $k \ge 40$ and move toward stability as $k \to 40$

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Growth Rates



Figure: The most unstable wave number increases with decreasing Bu. The dashed green line is an analytic approximation for $Bu = \infty$.

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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Linearization of Shallow Water

Background profile:

$$\eta^{b} = \eta^{b}(y), \ \ u^{b} = u^{b}(y) = -\eta^{b}(y)', \ \ v^{b} = 0.$$

Separable solution:

$$\eta^{\rho} = e^{ik(x-ct)}\widetilde{\eta}(y), \quad u^{\rho} = e^{ik(x-ct)}\widetilde{u}(y), \quad v^{\rho} = e^{ik(x-ct)}i\widetilde{v}(y)$$

Linearized equation:

$$c \begin{bmatrix} \tilde{u} \\ \tilde{v} \\ \tilde{\eta}/\sqrt{Bu} \end{bmatrix} = \frac{1}{Ro} \begin{bmatrix} u^{b}Ro & -1/k + \frac{(u^{b})'}{k}Ro & \sqrt{Bu} \\ -1/k & u^{b}Ro & -\frac{\sqrt{Bu}}{k}\partial \\ \sqrt{Bu} + \frac{Ro}{\sqrt{Bu}}\eta^{b} & \frac{\sqrt{Bu}}{k}\partial + \frac{Ro}{k\sqrt{Bu}}(\eta^{b}\partial + (\eta^{b})') & u^{b}Ro \end{bmatrix} \begin{bmatrix} \tilde{u} & \tilde{v} \\ \tilde{\eta}/\sqrt{Bu} & \tilde{u} \end{bmatrix}$$

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Growth Rates



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Growth Rates



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Rayleigh's Equation Sine Profile Instability Comparison with Shallow Water

Ageostrophic Instabilities



Figure: The spectrum is broken up by high/low divergence.

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Orthogonal Polynomials Relation to Instability Calculating Instability

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Orthogonal Polynomials Relation to Instability Calculating Instability

Orthogonal Polynomials on $\mathbb R$

$\mu(x)$ a measure on \mathbb{R} with finite moments.

Definition

The (normalized) **sequence of orthogonal polynomials** (SOP) $p_0(x), p_1(x), \ldots$ for μ satisfies

•
$$\int p_m(x)p_n(x)d\mu(x) = 0$$
 for $m \neq n$

•
$$\deg(p_n(x)) = n$$
 for all n

•
$$\int p_n(x)^2 d\mu(x) = 1$$

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Orthogonal Polynomials Relation to Instability Calculating Instability

Jacobi Matrices

Theorem

If $p_0(x), p_1(x), \ldots$ is a SOP for μ , then

 $xp_n(x) = a_np_{n+1}(x) + b_np_n(x) + a_{n-1}p_{n-1}(x).$

$$\begin{bmatrix} b_0 & a_0 & 0 & 0 & \dots \\ a_0 & b_1 & a_1 & 0 & \dots \\ 0 & a_1 & b_2 & a_2 & \dots \\ 0 & 0 & a_2 & b_2 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} p_0(x) \\ p_1(x) \\ p_2(x) \\ p_3(x) \\ \vdots \end{bmatrix} = x \begin{bmatrix} p_0(x) \\ p_1(x) \\ p_2(x) \\ p_3(x) \\ \vdots \end{bmatrix}$$

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Rayleigh's Equation

For $u^{b}(y) = \cos(y)$, Rayleigh's equation

$$f''(y) - \left(k^2 + \frac{-\cos(y) - c/\mathsf{Bu}}{\cos(y) - c}\right)f(y) = 0.$$

In spectral space:

$$\frac{1}{2}\frac{(\ell+1)^2+k^2-1}{\ell^2+k^2+1/\mathsf{Bu}}\hat{f}(\ell+1)+\frac{1}{2}\frac{(\ell-1)^2+k^2-1}{\ell^2+k^2+1/\mathsf{Bu}}\hat{f}(\ell-1)=c\hat{f}(\ell),$$

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Rayleigh's Equation

Setting

$$\hat{q}(\ell) = \frac{1}{\sqrt{2}} \left(\frac{\ell^2 + k^2 - 1}{\ell^2 + k^2 + 1/\mathsf{Bu}} \right)^{1/2}$$
$$\hat{g}(\ell) = (\ell^2 + k^2 - 1)^{1/2} (\ell^2 + k^2 + 1/\mathsf{Bu})^{1/2} \hat{f}(\ell)$$

We have

$$c\hat{g}(\ell)=\hat{q}(\ell)\hat{q}(\ell+1)\hat{g}(\ell+1)+\hat{q}(\ell)\hat{q}(\ell-1)\hat{g}(\ell-1).$$

For convenience, let

$$z_j = \widehat{q}(j)\widehat{q}(j+1)$$

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Orthogonal Polynomials Relation to Instability Calculating Instability

Eigenvectors of bi-infinite matrix



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Eigenvectors of Jacobi matrix

$$\widetilde{B} = \begin{bmatrix} 0 & 2z_0 & 0 & 0 & \dots \\ z_0 & 0 & z_1 & 0 & \dots \\ 0 & z_1 & 0 & z_2 & \dots \\ 0 & 0 & z_2 & 0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}.$$

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Eigenvectors of Jacobi matrix

$$\widetilde{B}^{2} = \begin{bmatrix} 2z_{0}^{2} & 0 & 2z_{0}z_{1} & 0 & \dots \\ 0 & 2z_{0}^{2} + z_{1}^{2} & 0 & z_{1}z_{2} & \dots \\ z_{0}z_{1} & 0 & z_{2}^{2} + z_{2}^{2} & 0 & \dots \\ 0 & z_{1}z_{2} & 0 & z_{2}^{2} + z_{3}^{2} & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

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Eigenvectors of Jacobi matrix

$$A = \begin{bmatrix} 2z_0^2 + z_1^2 & z_1z_2 & 0 & 0 & \dots \\ z_1z_2 & z_2^2 + z_3^2 & z_3z_4 & 0 & \dots \\ 0 & z_3z_4 & z_4^2 + z_5^2 & z_5z_6 & \dots \\ 0 & 0 & z_5z_6 & z_6^2 + z_7^2 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

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Spectrum of A

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Theorem (Casper)

The sequence of orthogonal polynomials $p_n(x)$ associated to A satisfies:

- each $p_n(x)$ has exactly one negative root r_{n1}
- -*r*_{n1} is monotone increasing
- -r_{n1} converges to the unique negative eigenvalue of A
- the limit is the growth rate

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Rotating Shallow Water Instability Analysis Analytic Methods for the Cosine Profile Calculating Instability



Figure: $|r_{n1}|$ vs *k* for various values of *n* at Burger number 1 and 100. Convergence is slower for larger Burger.

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Figure: The growth rate vs. wave number for various values of the Burger number. Predicts increasing max unstable wave number with decreasing Burger.

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Orthogonal Polynomials Relation to Instability Calculating Instability

Thank You!

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